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# **CUAV HackLink Quick start and Development Guide**

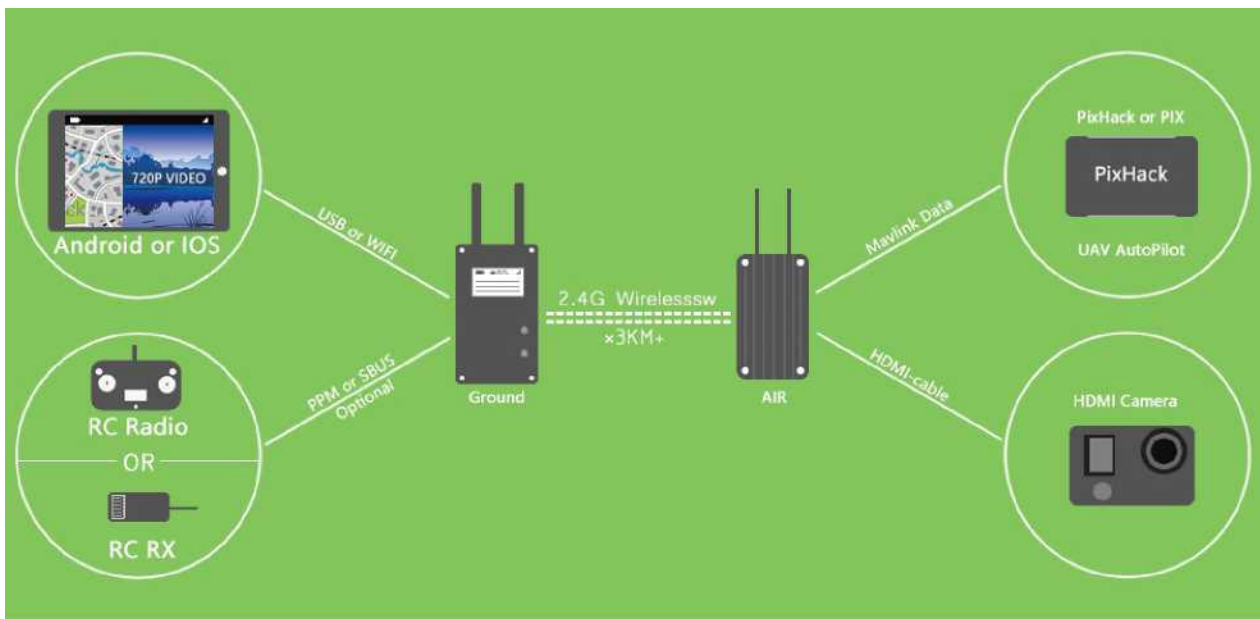
Revision record:

A version release finished in 2017-2-6.

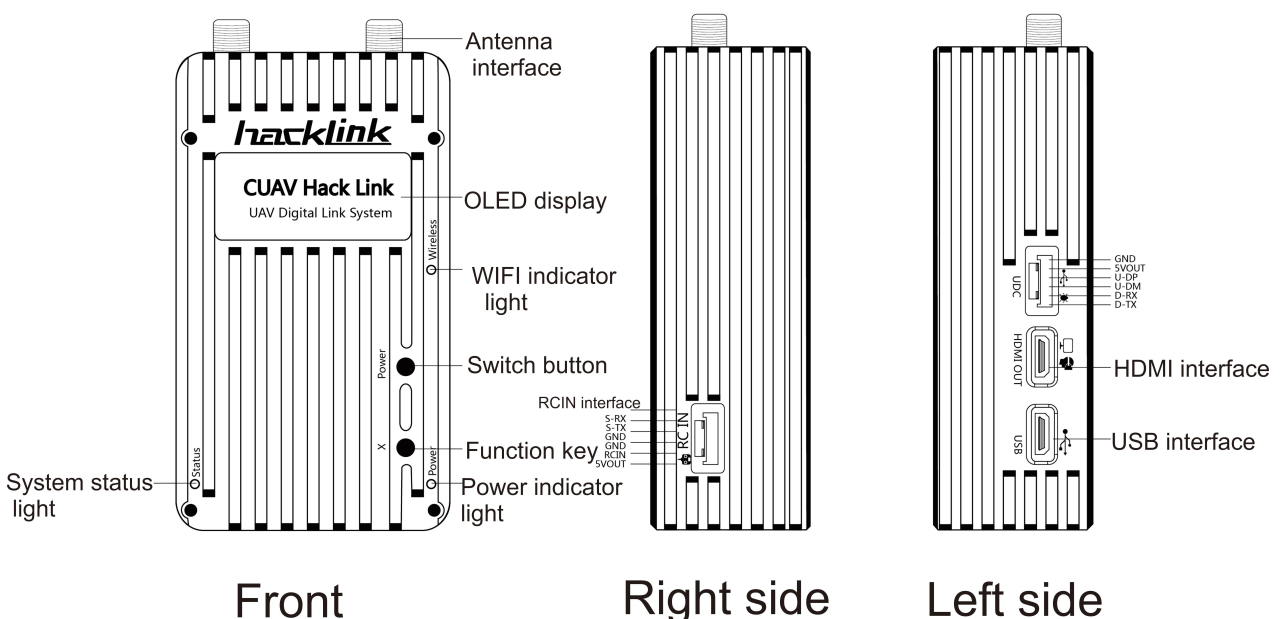
# Summary

- HackLink --a UAV digital link system with integration of HD graphics and data transfer
- Support 720P HD video transmission and MAVLINK protocol, as well as PPM & SBUS remote signal forwarding
- The realization of a link system can be on real-time HD video backhaul, UAV data interaction and the real time control of UAV
- Dual Mino technology, standard omnidirectional antenna distance 3KM, and 2.4G or 5.8G channel can be selected according to requirements.
- Use NXP high performance IMX6 processor for running LINUX system, suitable for second development (Compatible with 3DR SOLO development environment).
- The ground station terminal built-in OLED screen can display flight related state.
- HDMI output, it can be connected to the HDMI display and HDMI video glasses

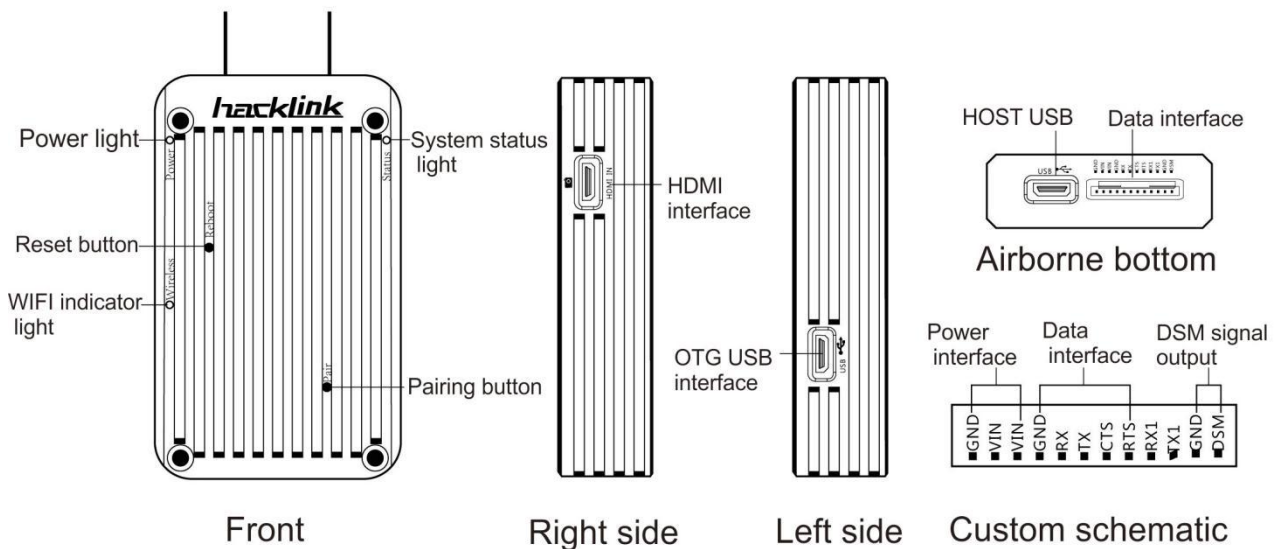
## System frame diagram



## Functional interface definition Ground end interface definition:



## Aircraft end interface definition:



## Technical specifications

-	-
Communication distance	2-3KM ideal environment omnidirectional antenna
Effective isotropic radiated power (EIRP)	500MW
Receiving sensitivity (1%PER)	-95dbm
Working frequency	2.4Ghz or 5.8Ghz (optional for purchase)
Antenna gain (airborne) UFL interface	2.0dBi
Antenna gain (ground side) SMA interface	5.0dBi
Working environment and physical parameters	
AIR airborne working voltage and current	5.0+/-0.2V 2A max
GR ground station charging voltage	5.0+/-0.2V
GR ground station operating current	2.1A max
GR ground station built in battery capacity	3.6V 3105mah
GR ground station OLED display resolution	white light 128 X64
Operating temperature range	-10~50℃
Dimension	Airborne terminal: 75mm(length) x45mm(width) x45mm(height) GR: 80mm(length) x45mm(width) x25mm(height)
Weight	AIR: 60g GR: 150g
Video input / output application equipment	
Video input format	HDMI:720P

Supporting camera	GOPRO3 GOPRO4 ant motion camera and other HDM cameras
Video output	MICRO HDMI720P30P
Support equipment	HDM input display or video glasses
Remote signal input and output	
Ground station support remote control signal standard	SBUS & PPM automatic recognition
Aircraft remote control signal output	DSM

## Default WIFI SSID and password

Default WIFI SSID: HackLink\_XXXXXX ( Last 6 digit of MAC address, Automatic generation )

Default password: cuavhlink

# HackLink Initial installation

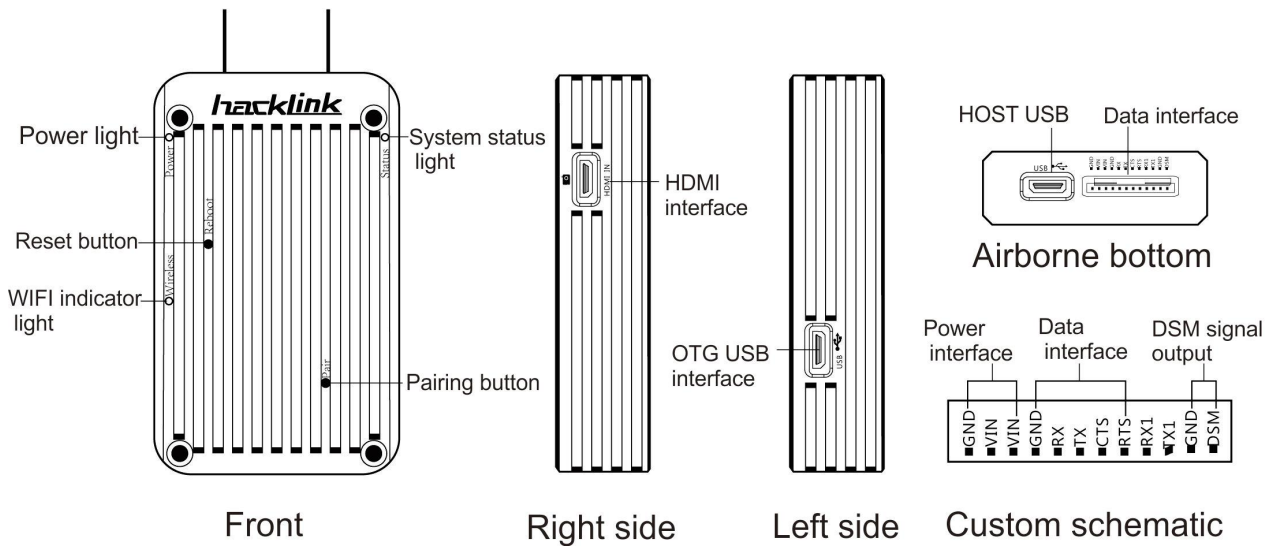
At present, only the PixHack or PixHawk wiring is optional , other mavlink flight may need to change the line

## In connection with the PixHack flight

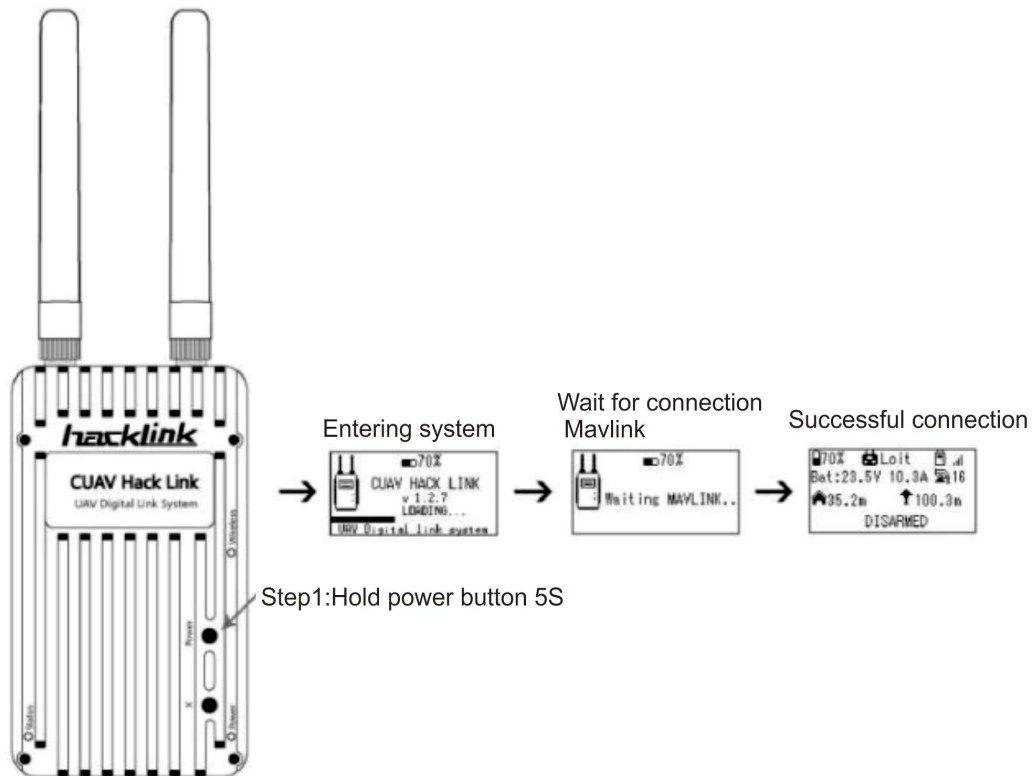
1. Insert the data interface of HackLink aircraft terminal in the RADIO transmission interface.
2. Supporting DC-DC module for power supply (support 2-7S battery)
3. Then insert the DSM remote control signal into the DSM interface of the flight control

Notes:

1. If the ground is not connected to the remote control or receiver, do not plug the DSM interface
2. If the flight control is connected to the receiver, do not insert the DSM interface simultaneously.







- After both ends powered on, aircraft end blue start status lights will flash, it indicates that the connection has not been successfully connected to the ground, at this time, pairing is needed.
- After both ends powered on, the AIR end blue light has become bright, but ground side OLED does not show flight data, but waiting mavlink, there is maybe problem in aircraft flight control terminal and communication, check the connection line and control settings (try to open the Telem control for setting).

How to connect a mobile phone or a computer, please refer to the software applicaion part.

Extended HDMI display

## HackLink ground terminal connects HDMI display or video glasses

HackLink ground end has a HDMI extended output interface, in theory, it can support any HDMI display or video glasses

Its output format : 30P Resolution 30P

Use the HDMI line to connect the HackLink ground to the monitor, which can be used to display HD videos.



Trouble shooting:



1. APP display normal, HDMI display can not be displayed properly

Solution: activate the camera again; if nothing is displayed, check the HDMI display connection line

2. Both APP and HDMI can not be displayed

Solution: check the camera settings, set the 720P output, it is also possible that the camera is not compatible

Re transmission by ground remote control

## HackLink ground access remote control signal

HackLink remote control re transmission

Access remote signal in HackLink GR RCIN, the DSM signal will be output to flight control by AIR

Support two standard remote control signals (SBUS and PPM), the two standards can be automatically identified, no need to set.

Note: the novice shall cautiously use this function, if the aircraft is not adjusted to the desired state, do not use the remote control re transmission function, so as to avoid the blast situation.

Advantages:

1. No receiver is needed on the plane
2. uniformity in distance and digital link
3. No co frequency interference problem
4. Disadvantages:
  1. After the signal is lost, there is a certain reconnection time between the aircraft and the ground station
  2. Add a certain delay

# Software application

## Compatible software

Currently HackLink support software are as follows

Computer terminal:

- Mission P | anner Unable to view video stream, used for digital transmission only )
- [QGroundControl](#) Video streams and data can be viewed interactively, but because of the QGC video decoder, the video is not fluent )

Android:

- [CUAV Hflight](#) CUAV official ground station, you can upgrade and set up operations ) Recommended
- 3DR SOLO (Unable used directly, then wifi SSID needs to be changed as sOïOLink\_XXXXXX )
- [QGroundControl](#) Video streams and data can be viewed interactively, but because of the QGC video decoder, the video is not fluent )

Apple :

- 3DR SOLO Unable to be used directly, the wifi SSID needs to be changed as... )

Download: Apple store search 3DR SOLO

# CUAV Hfight

## CUAV Official ground station

Download at: <http://fw.cuav.net/apk/>

System requirements: Android 4.4 or more

## Connect ground station via WIFI

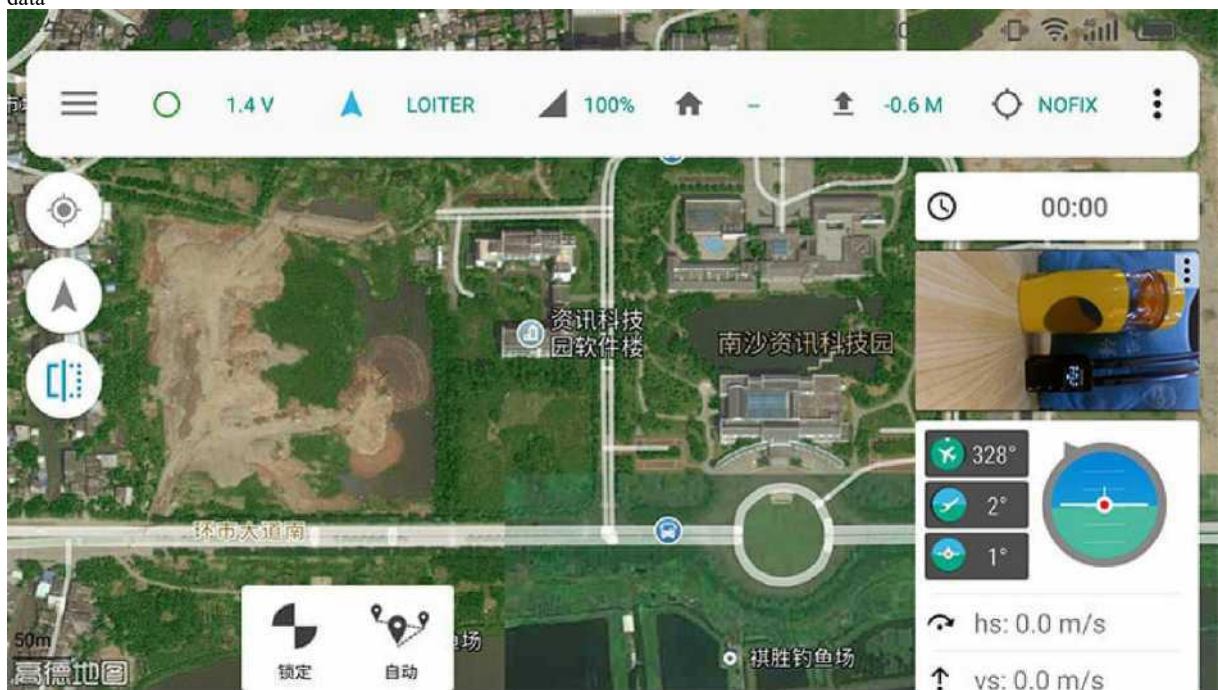
1. Download and install Android earth station
2. Digital link connecting flight control, aircraft powered on and ground end boot
3. Search HackLink\_xxxxxx, pass password and connected



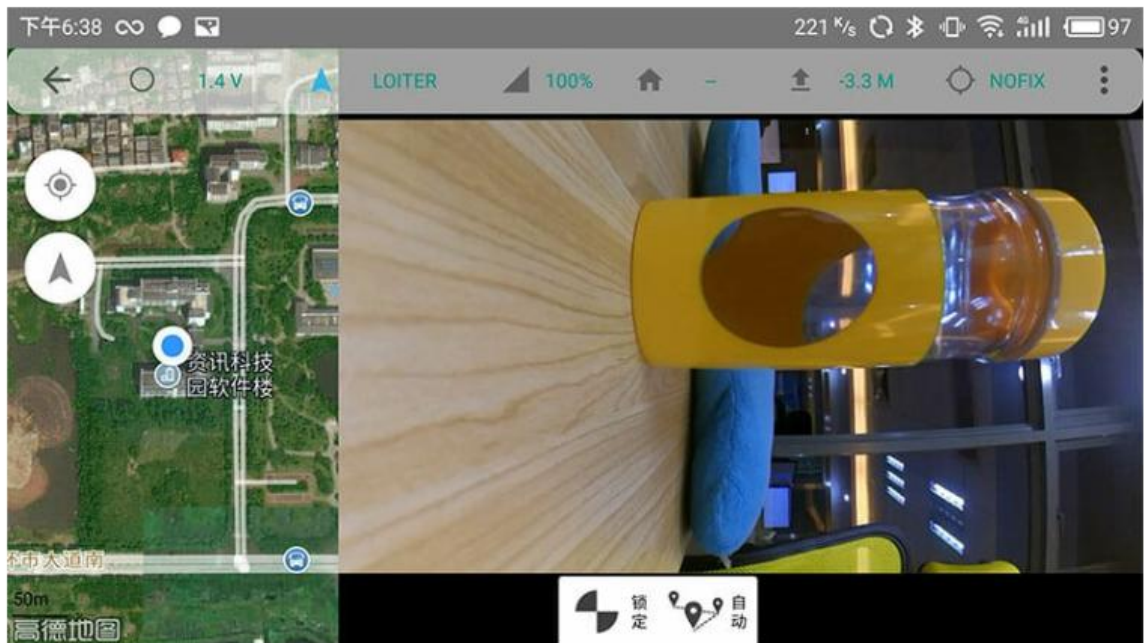
4. open CUAV Hfight software



5. Select UDP, click connection
6. After the connection is successful, you can see the video and flight data



7. Click on the video window to switch to the large screen display



## Change WIFI SSID and password

1. open the sidebar → system interface
2. \_XXXXXX
3. Popup dialog

If only changing password, you can type a password in the password box (more than 8 digits)



If you modify the SSID, you can change the name, no need to add the HackLink\_ prefix, the software will automatically identify and add

## Modify SSID, using 3DR SOLO software

If you need to change the SoloLink\_ prefix, type SoloLink\_123456 in the dialog and confirm.

## Upgrade the ground side MCU program

### 1. Get version information

- Use the ground station to connect the digital link
- Click on the sidebar→system options

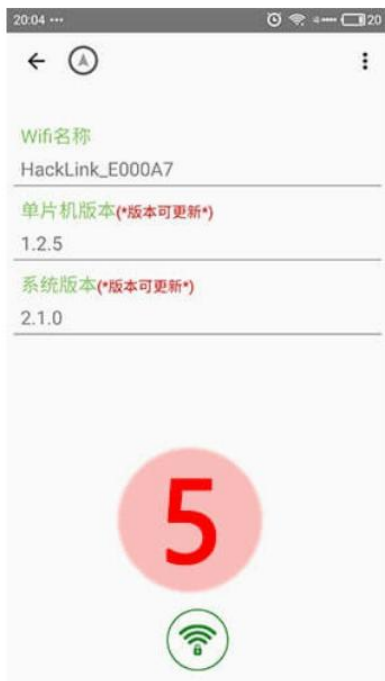


- The ground station will show that the information is updated successfully
  - Then disconnect WIFI and switch to the network connection
- ### 2. Get a new version of the file from the Internet
- When a new version is available, a new version is available for download
  - Click on the corresponding option to download the latest version to the local cache of the phone



### 3.Update MCU program to digital link

- Switch to Hacklink digital link WIFI network
- Open the sidebar→system options
- After the program is downloaded to the phone cache, you can see the prompt version can be updated



- Click on SCM options
- Update now?
- Click confirm, APP will update the firmware file to the digital link folder
- Then prompted to restart, the system will reboot after confirming, when system restarts, the MCU will be updated.

## Upgrade system

### 1.Get version information



Upgrade system needs to meet two conditions

- i. ground terminal power above 30% (more than 50%)
- ii. aircraft and the end of the ground has been normally matched

○Use the ground station to connect the digital link

○Click on the sidebar→ system options



○The ground station will show that the information is updated successfully

○ Then disconnect WIFI and switch to external network connection

2.Get a new version of the file from the Internet

○ When a new version is available, it is available for download

○Click on the system version (version available) option

○Pop-up dialog box to download the system version, then download it (System is relatively large, it may take some time to download).





### 3. update system to digital link

○ Switch to Hacklink digital link WIFI network

○ Open the sidebar → system options

○ After the program is downloaded to the phone cache, you can see the prompt version can be updated



○ Click on the system version (version update) option

○ Update now?

○ confirm, and APP will update the firmware file to the digital link folder



○ Then prompted to restart, the system will reboot after confirming, when system restarts, the MCU will be updated.

# Use QGC to connect HackLink

QGroundControl is a cross platform ground station software, including Windows version, Android version, apple version, etc.

Because it is compiled from the same set of code, so the operation is almost the same, the difference is relatively small, thus, this article only explain the use methods of Windows version and Android version

## Windows :

### 1.Install and connect network

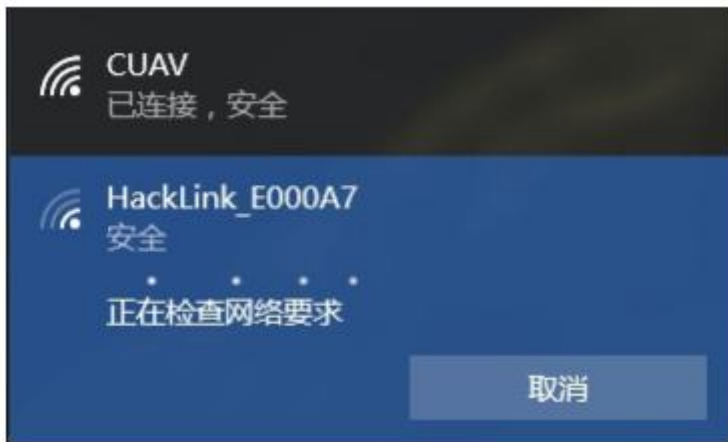
Before the connection, please ensure that the HackLink is normal and flight control has powered on

If not, check the hardware connection - the initial installation

Download at:

<https://s3-us-west-2.amazonaws.com/qgroundcontrol/latest/QGroundControl-installer.exe>

### 2.use the network connected to HackLink

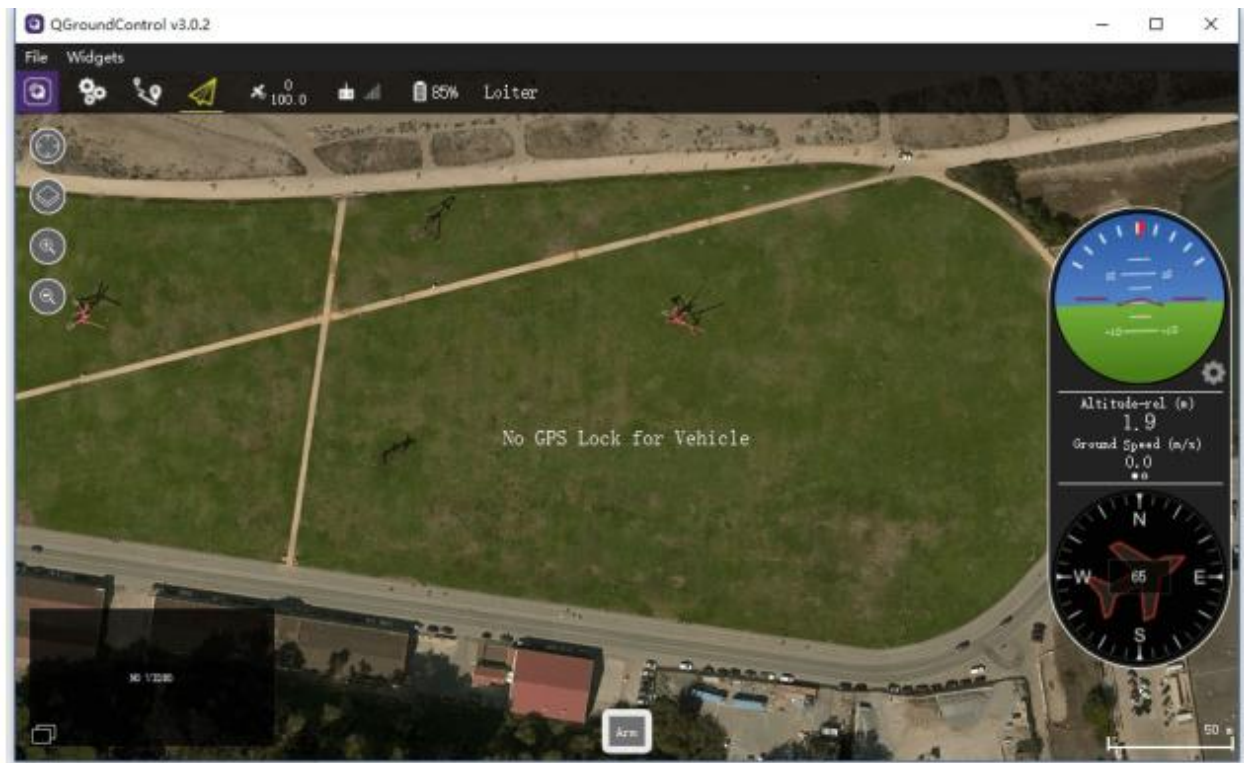


### 3.Install and open QGC software

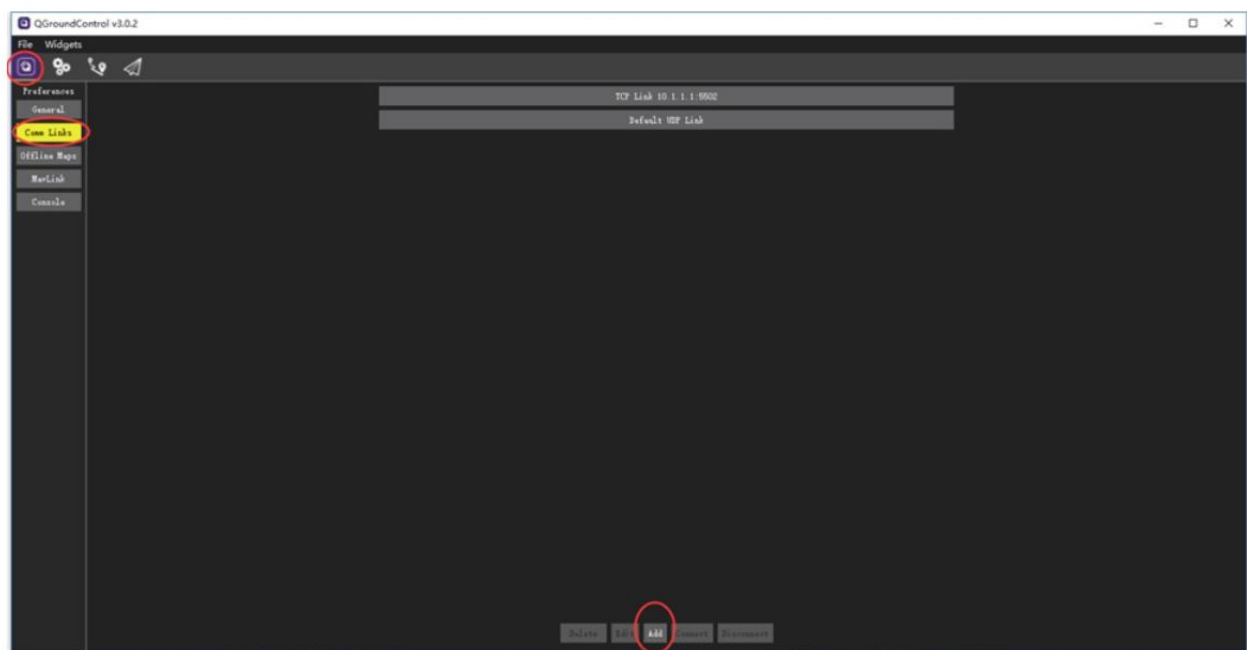


HackLink is used in UDPMavlink data broadcasting, as long as in the same network, open the QGC software will automatically connect to the flight control.

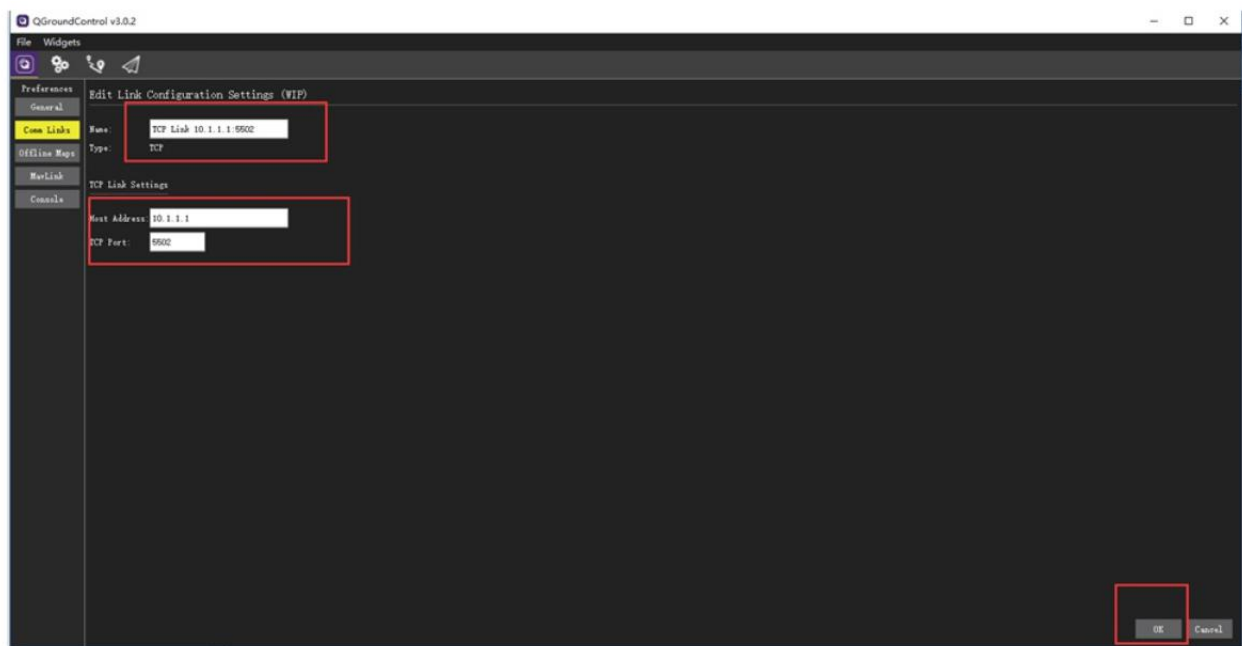
The following describes a new connection to allow the QGC to get the video stream



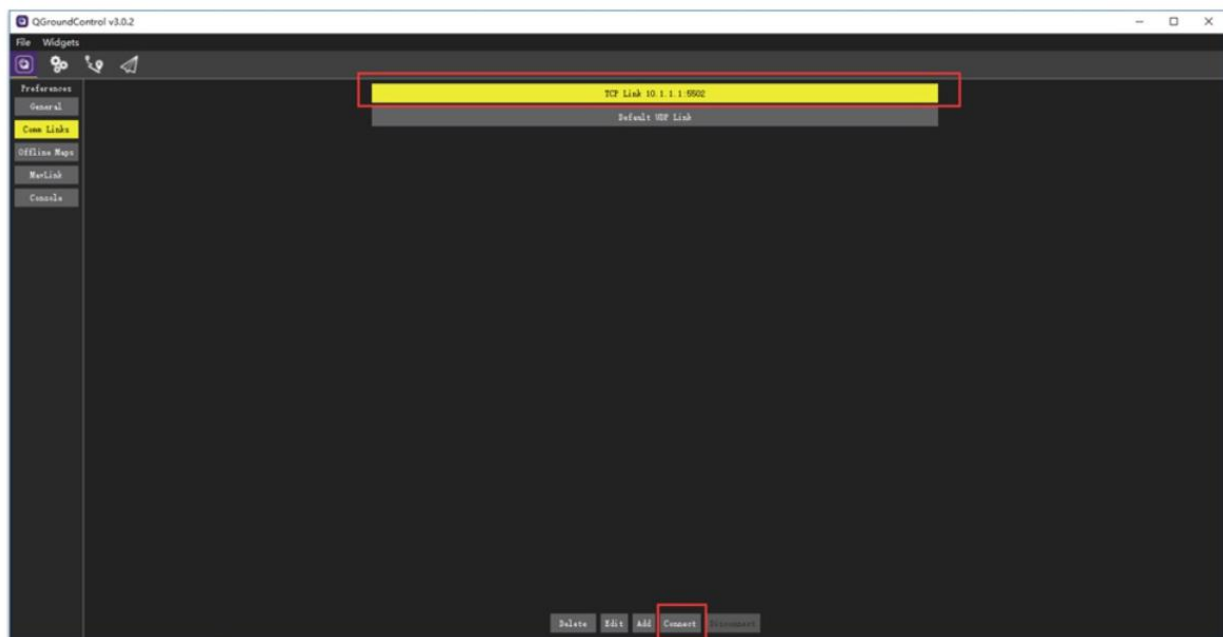
1. Enter the comm links option, ADD will add a new link



2. Host address: 10.1.1.1  
port: 5502, click OK.



3. Select new connection



4. Click connect, and then return to the main interface



Video and data available

Same settings for other platforms QGC, including Android QGC, apple QGC, linuxQGC, etc.. For QGC uses a soft decoding, video is not smooth

# pairing and restoring system

## HackLink

At present, the factory has done a good pairing operation, no need to do the pairing operation after receiving..

Only to upgrade the system or do a restore system operation, you need to re pairing/

## How to determine whether HackLink has been successfully matched

Status light (Power lamp red system status lamp blue wireless status lamp green).

Power on the AIR, turn on GR, and wait 1 minutes, after the system is started. The normal state should be as follows

GR :

Start light flashes (blue) (that has been started; Wireless state light (green) bright, wireless RF card is activated

AIR:

Start status light (blue)bright (Connected to GR), Wireless state light (green) bright, wireless RF card is activated



## pairing process

It is simple and requires only a few steps

1. Start and power on, waiting for indicators bright
2. Use a toothpick or pointed tool (such as paper clips and tweezers) to press Pair button for 5 seconds
3. After a period of time, OLED end will prompt to find a new AIR end
4. Press X key don't let go, after prompting paired, release the button



5. About 15 seconds later, the pairing is successful

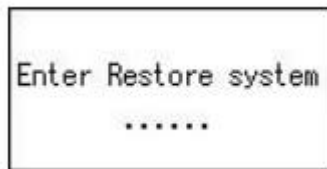


## Restore system operating instructions

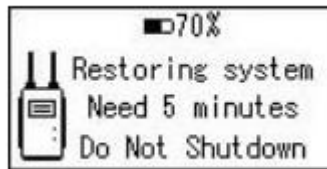
Note: make sure the battery is 20 % above before the restore of the system

Ground end restore process:

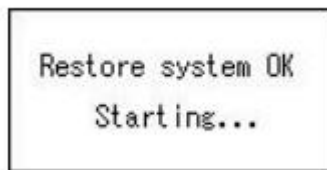
1. In shutdown state
2. Press the X key, then press the power button.
3. After the start , press X button, till OLED screen prompts to restore system.



4. after a period of time, the indicator will flash and OLED screen shows in restoring system.



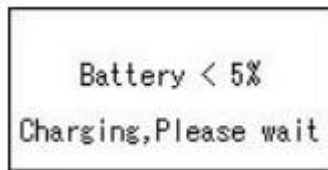
5. About 5 minutes later, the success of the restore system



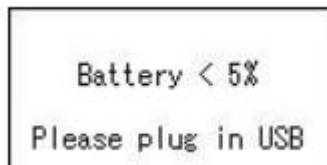
Aircraft end restore process:

- Like that of GR end, press the Pair button, then wait for blue light flashes
- Or press the Pair, and then press the reset button.
- The system will restart after restore, the state light will return to normal flashing state

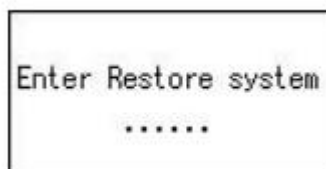
Detailed annotation on OLED display



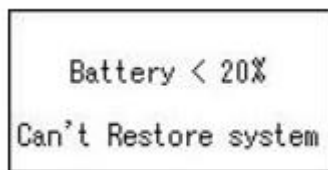
Battery less than 5% , unable to boot, charging, please wait.



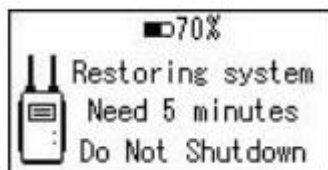
Battery less than 5% , unable to boot, please access the USB for charging



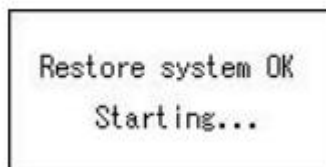
Enter the recovery system, wait.....



Battery power is less than 20%, unable to restore the system, please turn off, and charge till over 20% power for recovery system.

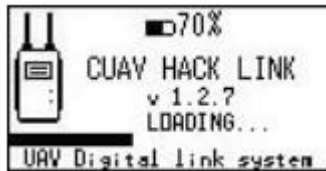


Ongoing recovery system, need 5 minutes, please do not shutdown

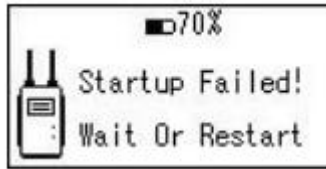


Recovery system is completed, the system is being restarted, please wait



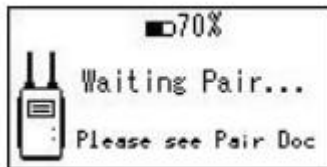


Boot load, please wait.

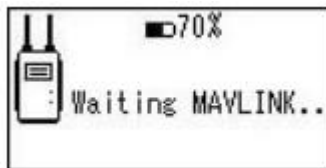


Boot load failed, please wait for the load to complete or shutdown for restart. There are reasons:

1. Hardware start up delay, waiting to start to complete
2. Hardware boot failure, shutdown restart required. If you start the system, please see the status lights.

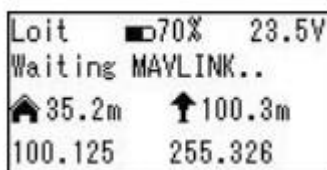


Waiting for the aircraft to launch the pairing, please click on the aircraft pairing, please refer to the pairing documentation..

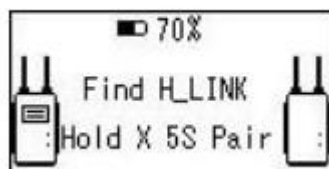


Waiting for the aircraft terminal MAVLINK data :

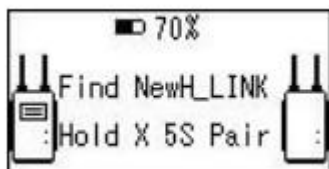
1. The plane did not connect the flight control
2. No MAVLINK data, check the pairing state



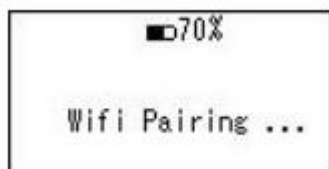
Wait MAVLINK data, and store information before shut down, including Flight mode, flight height away from home, battery voltage, GPS latitude and longitude information.



Searched an aircraft, hold down the X key for 5 seconds for pairing



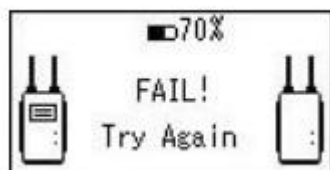
Searched an aircraft, hold down the X key for 5 seconds for pairing



Pairing, wait



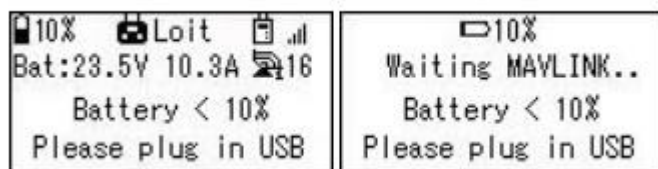
Paired



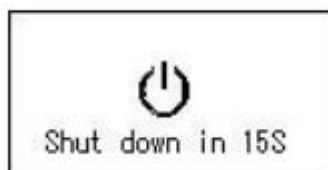
Fail, try again



Successful pairing , the normal display interface.



Battery less than 10%. Please connect to USB charging.



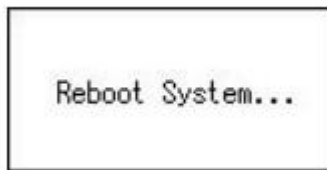
Shut down



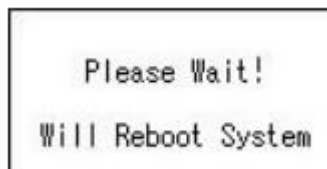
Shutdown fast charging interface.



Charging is complete, please unplug USB.



Modifying the WIFI name, automatically restart the system, please wait.



Please wait, the system will be rebooted

# FAQ

## APP download address

• [CUAVAPP](#)

## HDM output cannot display image

1. APP display normal, HDMI display can not display ; solution: the camera re boot
2. APP and HDM can not display.

Solution: check the camera settings, set the 720P output, it is also possible that the camera is not compatible

## How far can **HackLink** fly

Under the condition of no shelter and no interference, the farthest 3KM, even farther, but depending on the environment, if the interference is serious or occlusion, may be only a few hundred meters or even more short!

## How much power is transmitted

Dual 500MW , it can be adjusted by software : 10 - 500mW

## What channel is working on:

There are currently 2.4G version and 5.8G version

## What's the difference between 2.4G and 5.8G?

1. different frequency, wireless wave penetration is not the same, the lower the channel, the better penetration, 2.4G penetration is much better than 5.8G
2. 2.4G may be far away. However, because WIF is 2.4G, so it is prone to have interference or cause interference to 2.4G remote control
3. 5.8G penetration will be a little worse, but because the 5.8G device resources are not so much, the band is relatively clean, and it will not interfere with the 2.4G remote control
4. 5.8G actual video fluency, a little better than 2.4G, but 2.4G may have far distance

## What remote control signal can be supported on the ground

PPM and SBUS protocol remote control receiver signal, it is recommended to use the remote controller's output port signal directly into the HackLink

## How many channels support?

at most 8

## Power amplifier supported?

Support, but power amplifier for GR and AIR at the same time.

## Planar antenna supported?

Yes, Flat antenna gain will be much stronger than the omni-directional antenna, but the angle is relatively narrow, you need to be able to target the aircraft at all times

## How long can the built-in battery be used on the ground?

If continuous uninterrupted work, at least 3 hours

## How long does it take to recharge the ground end?

Built -in PMU support of fast charging , using a fast 2A charger, about 30 minutes or so, it can be charged, but charger current shall reach more than 2A

## Ground end resolution and material

self luminous screen, 128x32 resolution

## What can be displayed on the ground end?

1. Built in battery current

2. Signal strength of digital link
3. Aircraft altitude, distance from home, GPS coordinates, flight mode
4. After disconnection, the final height, GPS coordinates, flight mode

### How does HackLink pair (please refer to the manual for details)

1. Paired during ex factory
2. If reset , manually pair
3. After the aircraft end powered, waiting for the blue lights flashing, the green lights are often bright, press the pair of keys for 5 seconds
4. There will be a hint in 10 seconds, press the X key to complete the pairing

### How does **HackLink** restore default configuration (please refer to the manual for details)

1. AIR end: before power on, press the Pair key, wait for blue light, and let go if the blue light flashes, restore the system, do not power off in the process
2. GR end: press X button, then press POWER button, and after display, release, restore the system, after the success of the restore, the screen will have prompts
3. After restored, pairing and APP upgrading are required for normal work.

### Can **HackLink** connect OSD?

1. Negative, for traditional OSD is generated by analog video overlay, does not apply to HackLink digital system
2. Using mobile phone APP can simultaneously achieve video and data display

### Can **HackLink** connect to computer?

Yes, but MP can not have a video display, only the transmission of data, QGC can display both video and data

### How many S batteries shall be sued for providing power to **HackLink AIR end**?

1. The distributed module must be used to supply power to the aircraft end, and it can support the 3-7S battery
2. Or use 5V3A voltage regulator module to supply power to the aircraft end.